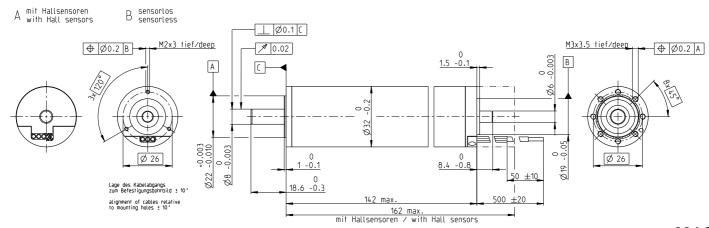
EC-4pole 32 Ø32 mm, brushless, 480 watt

Heavy Duty - for applications in oil



M 1:2

Stock program Standard program Special program (on request)		Part numbers			
A with Hall sensors B sensorless					
		397800			
Motor data (provisional)					
Values at nominal voltage and ambient temperature °C		25	100	150	200
1 Nominal voltage	V	48	48	48	48
2 No load speed	rpm	6420	6630	6750	6860
3 No load current	mA	482	222	212	216
4 Nominal speed ¹	rpm	4670	4420	4700	5340
5 Nominal torque ¹	mNm	804	762	596	379
6 Nominal current (max. continuous curre	ent) A	11.4	10.9	8.75	5.78
7 Stall torque	mNm	3350	2520	2150	1860
8 Stall current	Α	47.5	36.7	31.9	28.1
9 Max. efficiency	%	82	85	85	84
Characteristics					
10 Terminal resistance phase to phase	Ω	1.01	1.31	1.51	1.71
11 Terminal inductance phase to phase	mH	0.298	0.298	0.298	0.298
12 Torque constant	mNm/A	70.5	68.7	67.4	66.2
13 Speed constant	rpm/V	135	139	142	144
14 Speed / torque gradient	rpm/mNm	1.94	2.65	3.16	3.71
15 Mechanical time constant	ms	2.85	3.88	4.64	5.45
16 Rotor inertia	gcm ²	140	140	140	140

Values for operation in thermal equilibrium.

Operating range Thermal data n [rpm] Continuous operation 03 K/W 17 Thermal resistance housing-ambient 18 Thermal resistance winding-housing 360M 180M In observation of above listed thermal resistance 0.53 K/W (lines 17 and 18) and above listed ambient 19 Thermal time constant winding 18.4 s temperature, the maximum permissible winding 12000 20 Thermal time constant motor 129 stemperature will be reached during continuous 21 Ambient temperature -55...+200°C operation = thermal limit. 9000 22 Max. winding temperature +240°C Short term operation Mechanical data (preloaded ball bearings 6000 The motor may be briefly overloaded (recurring). 23 Max. speed 12000 rpm 24 Axial play at axial load < 20 N 0 mm 0.14 mm 3000 Assigned power rating > 20 N 25 Radial play preloaded 400 600 800 M [mNm] 200 26 Max. axial load (dynamic) 27 Max. force for press fits (static) 16 N 80 N 4 0 80 12 0 16 0 IIAI (static, shaft supported) 28 Max. radial load, 5 mm from flange 75 N Application

Other specifications

- 29 Number of pole pairs 30 Number of phases
- 31 Weight of motor

Connection A, motor cable PTFE (AWG 14) Motor winding 1 red black

Motor winding 2 Motor winding 3 white Connection A, sensors cable PTFE (AWG 24)

V_{Hall} 4.5...24 V GND green blue Hall sensor 1 red black Hall sensor 2 Hall sensor 3 white

Connection B, motor cable PTFE (AWG 14)

red Motor winding 1 Motor winding 2 black white Motor winding 3 Wiring diagram for Hall sensors see p. 67

General

- extreme temperature applications
- vibration tested (according to MIL-STD810F/Jan2000 860 g
 - operation in oil and high pressure (only minimal lubrication, therefore use under rated ambient conditions is not suggested)

Oil & Gas Industry

442_GP 42 HD

- oil, gas and geothermal wells

Modular system 434_GP 32 HD

This motor contains leaded solder. It therefore does not fulfill the requirements for the permitted maximum concentration of hazardous substances in accordance with the EC directive 2011/65/EC (RoHS) for all applications. The motor may therefore only be used for devices that are not subject to this directive.

Reference medium: Shell Tellus oil T32 Operation in oil of different viscosity will affect the motor data

Details on catalog page 52 *The Hall sensors in this motor are rated for ambient temperatures up to 150°C. The motor with Hall sensors is fully tested at 200°C in the final inspection. Nevertheless, the Hall sensors may temporarily fail below 200°C under certain conditions