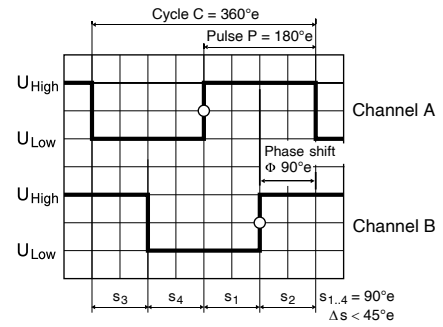
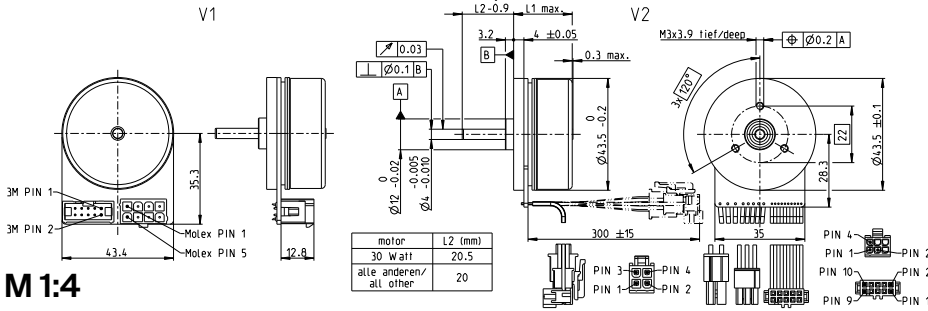




# Encoder MILE 256-2048 CPT, 2 channels, with line driver

Integrated into motor



Direction of rotation cw (definition cw p. 59)

M 1:4

- Stock program
- Standard program
- Special program (on request)

### Article Numbers

V1 with connector	673024	673025	673026	673027
V2 with cable and connector	673028	673029	673030	673031

Type	256	512	1024	2048
Counts per turn	256	512	1024	2048
Number of channels	2	2	2	2
Max. operating frequency (kHz)	1000	1000	1000	1000
Max. speed (rpm)	10 000	10 000	10 000	10 000



### maxon Modular System

+ Motor	Page	+ Gearhead	Page	+ Brake	Page	Overall length L1 max. [mm] / • see Gearhead
EC 45 flat, 70 W, A	299					28.4 / 28.4 / 28.4 / 28.4
EC 45 flat, 70 W, A	299	GP 32, 0.75 - 4.5 Nm	394			• / • / • / •
EC 45 flat, 70 W, A	299	GP 32, 1.0 - 6.0 Nm	398			• / • / • / •
EC 45 flat, 70 W, A	299	GP 42, 3.0 - 15.0 Nm	407			• / • / • / •
EC 45 flat, 70 W, A	299	GS 45, 0.5 - 2.0 Nm	409			• / • / • / •
EC 45 flat, 80 W, A	300					27.8 / 27.8 / 27.8 / 27.8
EC 45 flat, 80 W, A	300	GP 32, 0.75 - 4.5 Nm	394			• / • / • / •
EC 45 flat, 80 W, A	300	GP 32, 1.0 - 6.0 Nm	398			• / • / • / •
EC 45 flat, 80 W, A	300	GP 42, 3 - 15 Nm	407			• / • / • / •
EC 45 flat, 80 W, A	300	GS 45, 0.5 - 2.0 Nm	409			• / • / • / •
EC 45 flat, 120 W, A	301					33.8 / 33.8 / 33.8 / 33.8
EC 45 flat, 120 W, A	301	GP 32, 0.75 - 4.5 Nm	394			• / • / • / •
EC 45 flat, 120 W, A	301	GP 32, 1.0 - 6.0 Nm	398			• / • / • / •
EC 45 flat, 120 W, A	301	GP 42, 3 - 15 Nm	407			• / • / • / •
EC 45 flat, 120 W, A	301	GS 45, 0.5 - 2.0 Nm	409			• / • / • / •

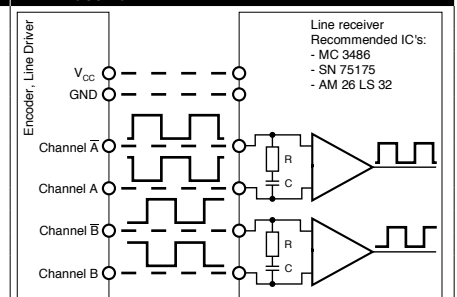
### Technical Data

Supply voltage $V_{CC}$	$5 B \pm 10\%$
Typical current draw	15 mA
Output signal	CMOS compatible
State length $s_n, 90^\circ e$ (1000 rpm)	$45 \dots 135^\circ e$
Signal rise time (typically, at $C_L = 25$ pF, $R_L = 1$ k $\Omega$ , 25 °C)	100 ns
Signal fall time (typically, at $C_L = 25$ pF, $R_L = 1$ k $\Omega$ , 25 °C)	100 ns
Operating temperature range	$-40 \dots +100^\circ C$
Moment of inertia of code wheel	$\leq 3.5$ gcm <sup>2</sup>
Output current per channel	max. 4 mA
Open collector output of the Hall sensors with integrated pull-up resistor	10 k $\Omega \pm 20\%$
Wiring diagram for Hall sensors see p. 59	

### Pin Allocation

Connection V1	Connection V2
<b>Motor + Sensors</b>	<b>Sensors (AWG 24)</b>
Pin 1 Hall sensor 1	Pin 1 Hall sensor 1
Pin 2 Hall sensor 2	Pin 2 Hall sensor 2
Pin 3 $V_{Hall}$ 4.5...18 VDC	Pin 3 Hall sensor 3
Pin 4 Motor winding 3	Pin 4 GND
Pin 5 Hall sensor 3	Pin 5 $V_{Hall}$ 4.5...18 VDC
Pin 6 GND	Pin 6 N.C.
Pin 7 Motor winding 1	<b>Motor (AWG 22)</b>
Pin 8 Motor winding 2	Pin 1 Motor winding 1
	Pin 2 Motor winding 2
	Pin 3 Motor winding 3
	Pin 4 Not connected
<b>Encoder</b>	<b>Encoder (AWG 28)</b>
Pin 1 N.C.	Pin 1 N.C.
Pin 2 $V_{CC}$	Pin 2 $V_{CC}$
Pin 3 GND	Pin 3 GND
Pin 4 N.C.	Pin 4 N.C.
Pin 5 Channel A	Pin 5 Channel A
Pin 6 Channel A	Pin 6 Channel A
Pin 7 Channel B	Pin 7 Channel B
Pin 8 Channel B	Pin 8 Channel B
Pin 9 Do not connect	Pin 9 Do not connect
Pin 10 Do not connect	Pin 10 Do not connect
<b>Pin type:</b>	
39-28-1083 Molex	43025-600 Molex
DIN 41651/EN 60603-13	39-01-2040 Molex
	DIN 41651/EN 60603-13

### Pin Allocation



Opt. terminal resistance  $R =$  typical 120  $\Omega$   
Capacitor  $C \geq 0.1$  nF per m line length

sensor