

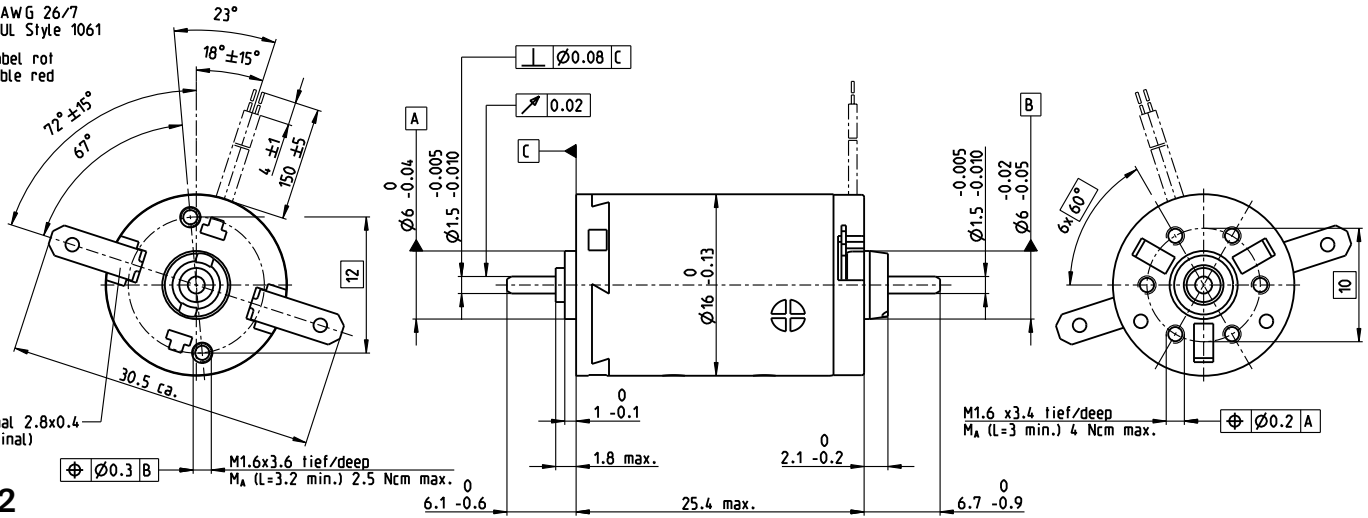
A-max 16 $\varnothing 16$ mm, graphite brushes, 2 watt

A-max

Kabel AWG 26/7
cable UL Style 1061



Kabel rot
cable red



M 3:2

- Stock program
- Standard program
- Special program (on request)

Part Numbers										
with terminals	110071	110072	110073	110074	110075	110076	110077	110078	110079	110080
with cables	139825	352870	352871	352872	352873	352874	352875	352876	352877	352878

Motor Data											
Values at nominal voltage											
1 Nominal voltage	V	1.5	3	6	9	12	14	15	18	21	30
2 No load speed	rpm	10200	11500	9360	11500	11500	11500	11000	10900	11300	10500
3 No load current	mA	282	164	65.6	54.6	41	35.1	31.1	25.9	23	15
4 Nominal speed	rpm	9010	8060	3280	5510	5460	5500	4860	4810	5100	4180
5 Nominal torque (max. continuous torque)	mNm	0.579	1.29	2.42	2.36	2.34	2.35	2.35	2.33	2.28	2.24
6 Nominal current (max. continuous current)	A	0.72	0.72	0.495	0.394	0.293	0.253	0.224	0.186	0.162	0.105
7 Stall torque	mNm	5.36	4.65	4.05	4.84	4.78	4.82	4.54	4.48	4.49	4.04
8 Stall current	A	4.1	2.03	0.727	0.704	0.521	0.451	0.378	0.311	0.276	0.164
9 Max. efficiency	%	54	51	49	52	52	52	51	51	50	48
Characteristics											
10 Terminal resistance	Ω	0.366	1.48	8.25	12.8	23	31.1	39.7	57.9	76.1	183
11 Terminal inductance	mH	0.017	0.052	0.306	0.467	0.83	1.13	1.42	2.05	2.61	6.01
12 Torque constant	mNm/A	1.31	2.29	5.57	6.88	9.17	10.7	12	14.4	16.3	24.7
13 Speed constant	rpm/V	7290	4170	1720	1390	1040	893	795	663	587	387
14 Speed/torque gradient	rpm/mNm	2040	2690	2540	2580	2620	2590	2630	2660	2750	2880
15 Mechanical time constant	ms	22.6	23.1	23.1	23.2	23.3	23.3	23.5	23.4	23.5	23.9
16 Rotor inertia	gcm ²	1.06	0.82	0.868	0.859	0.849	0.859	0.852	0.838	0.816	0.793

Specifications	Operating Range	Comments
Thermal data 17 Thermal resistance housing-ambient 29.8 K/W 18 Thermal resistance winding-housing 5.5 K/W 19 Thermal time constant winding 3.55 s 20 Thermal time constant motor 165 s 21 Ambient temperature -30...+85°C 22 Max. winding temperature +125°C Mechanical data (sleeve bearings) 23 Max. speed 11900 rpm 24 Axial play 0.05 - 0.15 mm 25 Radial play 0.012 mm 26 Max. axial load (dynamic) 0.8 N 27 Max. force for press fits (static) (static, shaft supported) 35 N / 280 N 28 Max. radial load, 5 mm from flange 1.4 N	Operating Range <p>Graph showing speed (rpm) vs torque (mNm) and current (A) for 2.0W power rating. The y-axis ranges from 4000 to 12000 rpm. The x-axis ranges from 0.2 to 3.0 mNm and 0.2 to 0.6 A. A red shaded area indicates the operating range, bounded by a curve and a vertical line at 2.0W. A point labeled 110073 is marked on the curve.</p>	Continuous operation In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient. = Thermal limit. Short term operation The motor may be briefly overloaded (recurring). Assigned power rating

maxon Modular System	Details on catalog page 38
Mechanical data (ball bearings) 23 Max. speed 11900 rpm 24 Axial play 0.05 - 0.15 mm 25 Radial play 0.025 mm 26 Max. axial load (dynamic) 2.2 N 27 Max. force for press fits (static) (static, shaft supported) 30 N / 280 N 28 Max. radial load, 5 mm from flange 7.8 N Other specifications 29 Number of pole pairs 1 30 Number of commutator segments 7 31 Weight of motor 22 g	<p>Spur Gearhead $\varnothing 16$ mm 0.01 - 0.1 Nm Page 375-378</p> <p>Planetary Gearhead $\varnothing 16$ mm 0.1 - 0.6 Nm Page 379/380</p> <p>Screw Drive $\varnothing 16$ mm Page 421-423</p> <p>Recommended Electronics: Notes Page 38 ESCON Module 24/2 500 ESCON 36/2 DC 500 EPOS4 Micro 24/5 509 EPOS4 Comp. 24/5 3-axes 511 EPOS4 Mod./Comp. 24/1.5 512</p> <p>Encoder MR 32 CPT, 2/3 channels Page 475</p> <p>Encoder MR 128/256/512 CPT, 2/3 channels Page 476</p>

Values listed in the table are nominal.
Explanation of the figures on page 82.

Option
Ball bearings in place of sleeve bearings